# SAULT COLLEGE OF APPLIED ARTS & TECHNOLOGY

SAULT STE. MARIE, ONTARIO

COURSE OUTLINE

Course Title:	MATHEMATICS
Code No	MTH 551-4
Program:	ELECTRICAL/ELECTRONIC TECHNOLOGY/COMPUTER ENGINEERIN
Semester:	III
Date:	JUNE, 1986
Author	J, REAL

New:

Revision:

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APPROVED:

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## MATHEMATICS

### COURSE NAME

#### PHILOSOPHY/GOALS:

When the student has successfully completed this course he/she will have demonstrated an acceptable understanding of the course material as listed elsewhere.

The student should then be able to apply this knowledge in his/her studies of other courses in the program where there are applications of these mathematical concepts.

Upon graduation, the student should be able to develop a good command of this subject matter through additional practice.

## METHOD OF ASSESSMENT (GRADING METHOD):

The student will be assessed by written tests only. There will be periodic topic tests at times mutually agreed upon (usually) by students and instructor. A letter grade will be assigned for the student's progress report based upon a weighted average of the student's best results-

See also the Mathematics department \* s annual publication "To The Mathematics Student" which is presented to the students early in each academic year.

#### TEXTBOOK(S):

Technical Mathematics with Calculus - Calter

# MTH 55 1-4

COURSE NUMBER

- 3 -MTH 551-4

TOPIC NO.	PERIODS	TOPIC DESCRIPTION A	SSIGNME	NT REFERENCE
	10	<u>Analytic Geometry</u> - (Conic Sections)		Ch. 21
		Circle Parabola Ellipse Hyperbola	Ex. 21- 21- 21- 21-	2 3
	18	<u>Deratives of</u> Algebraic Functions -		Ch. 22
		Limits The derivative - average and instantaneou rate of change. Delta method Rules for derivatives Chain rule Product and Quotient rul	22- 22- 22-	2 3 4
		Implicit relations Higher order derivatives	22-	6
		<u>Graphical Applications</u> of Derivatives -		Ch. 23
		Tangents and Normals Maximum and Minimum poin Inflection points Newton's Method of solving eqns- Curve sketching	Ex. 23- ts 23- 23- 23- 23-	2 3 4
		<u>More Applications of</u> Derivatives -		Ch. 24
		Rate of Change Motion of a point (velocity and acceleration)	Ex 24- 24-	
		Related rates Maximum-minimum applications Differentials (approximate change,	24 - 24 - 24 -	4
		error)		

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